TABLE OF INFORMATION DEVELOPED FOR 2012 (see note on cover page)

CONSTANTS AND CONVERSION FACTORS	
Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude, $e = 1.60 \times 10^{-19}$ C
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	1 electron volt, $1\text{ eV} = 1.60 \times 10^{-19}$ J
Electron mass, $m_e = 9.11 \times 10^{-31}$ kg	Speed of light, $c = 3.00 \times 10^{8}$ m/s
Avogadro's number, $N_0 = 6.02 \times 10^{23}$ mol^{-1}	Universal gravitational constant, $G = 6.67 \times 10^{-11}$ m^3/kg$\cdot$s^2
Universal gas constant, $R = 8.31$ J/(mol$\cdot$K)	Acceleration due to gravity at Earth's surface, $g = 9.8$ m/s^2
Boltzmann's constant, $k_B = 1.38 \times 10^{-23}$ J/K	

1 unified atomic mass unit,	$1\text{ u} = 1.66 \times 10^{-27}\text{ kg} = 931\text{ MeV}/c^2$
Planck's constant,	$h = 6.63 \times 10^{-34}\text{ J}\cdot\text{s} = 4.14 \times 10^{-15}\text{ eV}\cdot\text{s}$
	$hc = 1.99 \times 10^{-25}\text{ J}\cdot\text{m} = 1.24 \times 10^{3}\text{ eV}\cdot\text{nm}$
Vacuum permittivity,	$\epsilon_0 = 8.85 \times 10^{-12}\text{ C}^2/\text{N}\cdot\text{m}^2$
Coulomb's law constant,	$k = 1/4\pi\epsilon_0 = 9.0 \times 10^{9}\text{ N}\cdot\text{m}^2/\text{C}^2$
Vacuum permeability,	$\mu_0 = 4\pi \times 10^{-7}\text{ (T}\cdot\text{m)/A}$
Magnetic constant,	$k' = \mu_0/4\pi = 1 \times 10^{-7}\text{ (T}\cdot\text{m)/A}$
1 atmosphere pressure,	$1\text{ atm} = 1.0 \times 10^{5}\text{ N/m}^2 = 1.0 \times 10^{5}\text{ Pa}$

UNIT SYMBOLS								
	meter,	m	mole,	mol	watt,	W	farad,	F
	kilogram,	kg	hertz,	Hz	coulomb,	C	tesla,	T
	second,	s	newton,	N	volt,	V	degree Celsius,	°C
	ampere,	A	pascal,	Pa	ohm,	Ω	electron-volt,	eV
	kelvin,	K	joule,	J	henry,	H		

PREFIXES

Factor	Prefix	Symbol
10^{9}	giga	G
10^{6}	mega	M
10^{3}	kilo	k
10^{-2}	centi	c
10^{-3}	milli	m
10^{-6}	micro	μ
10^{-9}	nano	n
10^{-12}	pico	p

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES

θ	$0°$	$30°$	$37°$	$45°$	$53°$	$60°$	$90°$
$\sin\theta$	0	$1/2$	$3/5$	$\sqrt{2}/2$	$4/5$	$\sqrt{3}/2$	1
$\cos\theta$	1	$\sqrt{3}/2$	$4/5$	$\sqrt{2}/2$	$3/5$	$1/2$	0
$\tan\theta$	0	$\sqrt{3}/3$	$3/4$	1	$4/3$	$\sqrt{3}$	∞

The following conventions are used in this exam.

I. Unless otherwise stated, the frame of reference of any problem is assumed to be inertial.

II. The direction of any electric current is the direction of flow of positive charge (conventional current).

III. For any isolated electric charge, the electric potential is defined as zero at an infinite distance from the charge.

*IV. For mechanics and thermodynamics equations, *W* represents the work done <u>on</u> a system.

*Not on the Table of Information for Physics C, since Thermodynamics is not a Physics C topic.

ADVANCED PLACEMENT PHYSICS B EQUATIONS DEVELOPED FOR 2012

NEWTONIAN MECHANICS

$v = v_0 + at$

$x = x_0 + v_0 t + \frac{1}{2}at^2$

$v^2 = v_0^2 + 2a(x - x_0)$

$\Sigma \mathbf{F} = \mathbf{F}_{net} = m\mathbf{a}$

$F_{fric} \le \mu N$

$a_c = \frac{v^2}{r}$

$\tau = rF \sin\theta$

$\mathbf{p} = m\mathbf{v}$

$\mathbf{J} = \mathbf{F}\Delta t = \Delta\mathbf{p}$

$K = \frac{1}{2}mv^2$

$\Delta U_g = mgh$

$W = F\Delta r \cos\theta$

$P_{avg} = \frac{W}{\Delta t}$

$P = Fv\cos\theta$

$\mathbf{F}_s = -k\mathbf{x}$

$U_s = \frac{1}{2}kx^2$

$T_s = 2\pi\sqrt{\frac{m}{k}}$

$T_p = 2\pi\sqrt{\frac{\ell}{g}}$

$T = \frac{1}{f}$

$F_G = -\frac{Gm_1m_2}{r^2}$

$U_G = -\frac{Gm_1m_2}{r}$

a = acceleration
F = force
f = frequency
h = height
J = impulse
K = kinetic energy
k = spring constant
ℓ = length
m = mass
N = normal force
P = power
p = momentum
r = radius or distance
T = period
t = time
U = potential energy
v = velocity or speed
W = work done on a system
x = position
μ = coefficient of friction
θ = angle
τ = torque

ELECTRICITY AND MAGNETISM

$F = \frac{kq_1q_2}{r^2}$

$\mathbf{E} = \frac{\mathbf{F}}{q}$

$U_E = qV = \frac{kq_1q_2}{r}$

$E_{avg} = -\frac{V}{d}$

$V = k\left(\frac{q_1}{r_1} + \frac{q_2}{r_2} + \frac{q_3}{r_3} + \ldots\right)$

$C = \frac{Q}{V}$

$C = \frac{\epsilon_0 A}{d}$

$U_c = \frac{1}{2}QV = \frac{1}{2}CV^2$

$I_{avg} = \frac{\Delta Q}{\Delta t}$

$R = \frac{\rho\ell}{A}$

$V = IR$

$P = IV$

$C_p = C_1 + C_2 + C_3 + \ldots$

$\frac{1}{C_s} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \ldots$

$R_s = R_1 + R_2 + R_3 + \ldots$

$\frac{1}{R_p} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \ldots$

$F_B = qvB\sin\theta$

$F_B = BI\ell\sin\theta$

$B = \frac{\mu_0 I}{2\pi r}$

$\phi_m = BA\cos\theta$

$\mathcal{E}_{avg} = -\frac{\Delta\phi_m}{\Delta t}$

$\mathcal{E} = B\ell v$

A = area
B = magnetic field
C = capacitance
d = distance
E = electric field
$\mathcal{E}$ = emf
F = force
I = current
ℓ = length
P = power
Q = charge
q = point charge
R = resistance
r = distance
t = time
U = potential (stored) energy
V = electric potential or potential difference
v = velocity or speed
ρ = resistivity
θ = angle
ϕ_m = magnetic flux

ADVANCED PLACEMENT PHYSICS B EQUATIONS DEVELOPED FOR 2012

FLUID MECHANICS AND THERMAL PHYSICS

$\rho = m/V$

$P = P_0 + \rho g h$

$F_{buoy} = \rho V g$

$A_1 v_1 = A_2 v_2$

$P + \rho g y + \frac{1}{2}\rho v^2 = \text{const.}$

$\Delta \ell = \alpha \ell_0 \Delta T$

$H = \dfrac{kA\,\Delta T}{L}$

$P = \dfrac{F}{A}$

$PV = nRT = Nk_BT$

$K_{avg} = \frac{3}{2}k_BT$

$v_{rms} = \sqrt{\dfrac{3RT}{M}} = \sqrt{\dfrac{3k_BT}{\mu}}$

$W = -P\Delta V$

$\Delta U = Q + W$

$e = \left|\dfrac{W}{Q_H}\right|$

$e_c = \dfrac{T_H - T_C}{T_H}$

A = area
e = efficiency
F = force
h = depth
H = rate of heat transfer
k = thermal conductivity
K_{avg} = average molecular kinetic energy
ℓ = length
L = thickness
m = mass
M = molar mass
n = number of moles
N = number of molecules
P = pressure
Q = heat transferred to a system
T = temperature
U = internal energy
V = volume
v = velocity or speed
v_{rms} = root-mean-square velocity
W = work done on a system
y = height
α = coefficient of linear expansion
μ = mass of molecule
ρ = density

ATOMIC AND NUCLEAR PHYSICS

$E = hf = pc$

$K_{max} = hf - \phi$

$\lambda = \dfrac{h}{p}$

$\Delta E = (\Delta m)c^2$

E = energy
f = frequency
K = kinetic energy
m = mass
p = momentum
λ = wavelength
ϕ = work function

WAVES AND OPTICS

$v = f\lambda$

$n = \dfrac{c}{v}$

$n_1 \sin\theta_1 = n_2 \sin\theta_2$

$\sin\theta_c = \dfrac{n_2}{n_1}$

$\dfrac{1}{s_i} + \dfrac{1}{s_0} = \dfrac{1}{f}$

$M = \dfrac{h_i}{h_0} = -\dfrac{s_i}{s_0}$

$f = \dfrac{R}{2}$

$d\sin\theta = m\lambda$

$x_m \approx \dfrac{m\lambda L}{d}$

d = separation
f = frequency or focal length
h = height
L = distance
M = magnification
m = an integer
n = index of refraction
R = radius of curvature
s = distance
v = speed
x = position
λ = wavelength
θ = angle

GEOMETRY AND TRIGONOMETRY

Rectangle
$A = bh$

Triangle
$A = \frac{1}{2}bh$

Circle
$A = \pi r^2$
$C = 2\pi r$

Rectangular Solid
$V = \ell wh$

Cylinder
$V = \pi r^2 \ell$
$S = 2\pi r\ell + 2\pi r^2$

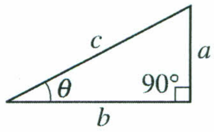
Sphere
$V = \frac{4}{3}\pi r^3$
$S = 4\pi r^2$

Right Triangle
$a^2 + b^2 = c^2$

$\sin\theta = \dfrac{a}{c}$

$\cos\theta = \dfrac{b}{c}$

$\tan\theta = \dfrac{a}{b}$



A = area
C = circumference
V = volume
S = surface area
b = base
h = height
ℓ = length
w = width
r = radius

ADVANCED PLACEMENT PHYSICS C EQUATIONS DEVELOPED FOR 2012

MECHANICS

$v = v_0 + at$

$x = x_0 + v_0 t + \frac{1}{2}at^2$

$v^2 = v_0^2 + 2a(x - x_0)$

$\sum \mathbf{F} = \mathbf{F}_{net} = m\mathbf{a}$

$\mathbf{F} = \frac{d\mathbf{p}}{dt}$

$\mathbf{J} = \int \mathbf{F}\,dt = \Delta\mathbf{p}$

$\mathbf{p} = m\mathbf{v}$

$F_{fric} \le \mu N$

$W = \int \mathbf{F} \cdot d\mathbf{r}$

$K = \frac{1}{2}mv^2$

$P = \frac{dW}{dt}$

$P = \mathbf{F} \cdot \mathbf{v}$

$\Delta U_g = mgh$

$a_c = \frac{v^2}{r} = \omega^2 r$

$\boldsymbol{\tau} = \mathbf{r} \times \mathbf{F}$

$\sum \boldsymbol{\tau} = \boldsymbol{\tau}_{net} = I\boldsymbol{\alpha}$

$I = \int r^2 dm = \sum mr^2$

$\mathbf{r}_{cm} = \sum m\mathbf{r} / \sum m$

$v = r\omega$

$\mathbf{L} = \mathbf{r} \times \mathbf{p} = I\boldsymbol{\omega}$

$K = \frac{1}{2}I\omega^2$

$\omega = \omega_0 + \alpha t$

$\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$

a = acceleration
F = force
f = frequency
h = height
I = rotational inertia
J = impulse
K = kinetic energy
k = spring constant
ℓ = length
L = angular momentum
m = mass
N = normal force
P = power
p = momentum
r = radius or distance
$\mathbf{r}$ = position vector
T = period
t = time
U = potential energy
v = velocity or speed
W = work done on a system
x = position
μ = coefficient of friction
θ = angle
τ = torque
ω = angular speed
α = angular acceleration
ϕ = phase angle

$\mathbf{F}_s = -k\mathbf{x}$

$U_s = \frac{1}{2}kx^2$

$x = x_{\max}\cos(\omega t + \phi)$

$T = \frac{2\pi}{\omega} = \frac{1}{f}$

$T_s = 2\pi\sqrt{\frac{m}{k}}$

$T_p = 2\pi\sqrt{\frac{\ell}{g}}$

$\mathbf{F}_G = -\frac{Gm_1m_2}{r^2}\hat{\mathbf{r}}$

$U_G = -\frac{Gm_1m_2}{r}$

ELECTRICITY AND MAGNETISM

$F = \frac{1}{4\pi\epsilon_0}\frac{q_1q_2}{r^2}$

$\mathbf{E} = \frac{\mathbf{F}}{q}$

$\oint \mathbf{E} \cdot d\mathbf{A} = \frac{Q}{\epsilon_0}$

$E = -\frac{dV}{dr}$

$V = \frac{1}{4\pi\epsilon_0}\sum_i \frac{q_i}{r_i}$

$U_E = qV = \frac{1}{4\pi\epsilon_0}\frac{q_1q_2}{r}$

$C = \frac{Q}{V}$

$C = \frac{\kappa\epsilon_0 A}{d}$

$C_p = \sum_i C_i$

$\frac{1}{C_s} = \sum_i \frac{1}{C_i}$

$I = \frac{dQ}{dt}$

$U_c = \frac{1}{2}QV = \frac{1}{2}CV^2$

$R = \frac{\rho\ell}{A}$

$\mathbf{E} = \rho\mathbf{J}$

$I = Nev_d A$

$V = IR$

$R_s = \sum_i R_i$

$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$

$P = IV$

$\mathbf{F}_M = q\mathbf{v} \times \mathbf{B}$

A = area
B = magnetic field
C = capacitance
d = distance
E = electric field
$\mathcal{E}$ = emf
F = force
I = current
J = current density
L = inductance
ℓ = length
n = number of loops of wire per unit length
N = number of charge carriers per unit volume
P = power
Q = charge
q = point charge
R = resistance
r = distance
t = time
U = potential or stored energy
V = electric potential
v = velocity or speed
ρ = resistivity
ϕ_m = magnetic flux
κ = dielectric constant

$\oint \mathbf{B} \cdot d\boldsymbol{\ell} = \mu_0 I$

$d\mathbf{B} = \frac{\mu_0}{4\pi}\frac{I\,d\boldsymbol{\ell} \times \mathbf{r}}{r^3}$

$\mathbf{F} = \int I\,d\boldsymbol{\ell} \times \mathbf{B}$

$B_s = \mu_0 nI$

$\phi_m = \int \mathbf{B} \cdot d\mathbf{A}$

$\mathcal{E} = \oint \mathbf{E} \cdot d\boldsymbol{\ell} = -\frac{d\phi_m}{dt}$

$\mathcal{E} = -L\frac{dI}{dt}$

$U_L = \frac{1}{2}LI^2$

ADVANCED PLACEMENT PHYSICS C EQUATIONS DEVELOPED FOR 2012

GEOMETRY AND TRIGONOMETRY

Rectangle

$A = bh$

Triangle

$A = \frac{1}{2}bh$

Circle

$A = \pi r^2$

$C = 2\pi r$

Rectangular Solid

$V = \ell wh$

Cylinder

$V = \pi r^2 \ell$

$S = 2\pi r\ell + 2\pi r^2$

Sphere

$V = \frac{4}{3}\pi r^3$

$S = 4\pi r^2$

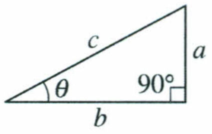
Right Triangle

$a^2 + b^2 = c^2$

$\sin\theta = \frac{a}{c}$

$\cos\theta = \frac{b}{c}$

$\tan\theta = \frac{a}{b}$



A = area
C = circumference
V = volume
S = surface area
b = base
h = height
ℓ = length
w = width
r = radius

CALCULUS

$$\frac{df}{dx} = \frac{df}{du}\frac{du}{dx}$$

$$\frac{d}{dx}\left(x^n\right) = nx^{n-1}$$

$$\frac{d}{dx}\left(e^x\right) = e^x$$

$$\frac{d}{dx}(\ln x) = \frac{1}{x}$$

$$\frac{d}{dx}(\sin x) = \cos x$$

$$\frac{d}{dx}(\cos x) = -\sin x$$

$$\int x^n\,dx = \frac{1}{n+1}x^{n+1},\ n \neq -1$$

$$\int e^x\,dx = e^x$$

$$\int \frac{dx}{x} = \ln|x|$$

$$\int \cos x\,dx = \sin x$$

$$\int \sin x\,dx = -\cos x$$